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1 2 3	A geomorphic enthalpy method: Description and application to the evolution of fluvial-deltas under sea-level cycles					
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12	Montclair, NJ 07043.					
13	Link to the code: https://github.com/JorgeMSU/1D-enthalpy-method					
14	Highlights:					
15	• Enthalpy-like solution to study fluvio-deltaic dynamics under sea-level variations.					
16	• Model produces stratigraphic profiles under a wide range of sea-level curves.					
17	• Time lags in system response can lead to river incision during the sea-level rise.					
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<u>Authorship statement:</u> WA and JLT developed the theory and performed the computations with input from VV. JLT and WA wrote the manuscript with input from VV. JLT designed and directed the project.

22 Abstract

Fluvial deltas are composites of two primary sedimentary environments: a depositional fluvial 23 region and an offshore region. The fluvial region is defined by two geomorphic moving 24 boundaries: an alluvial-bedrock transition (ABT), which separates the sediment prism from the 25 non-erodible bedrock basement, and the shoreline (SH), where the delta meets the ocean. The 26 27 trajectories of these boundaries in time and space define the evolution of the shape of the sedimentary prism, and are often used as stratigraphic indicators, particularly in seismic studies, 28 of changes in relative sea level and the identification of stratigraphic sequences. In order to better 29 30 understand the relative role of sea-level variations, sediment supply, and basin geometry on the evolution of the ABT and SH, we develop a forward stratigraphic model that accounts for 31 curvature changes of the fluvial surface and treats the SH and ABT as moving boundaries (i.e., 32 internal boundaries that are not known a priori and their location must be calculated as part of the 33 solution to the overall problem). This forward model extends a numerical technique from heat 34 transfer (i.e., enthalpy method), previously applied to the evolution of sedimentary basins, to 35 account for sea-level variations, including eustatic sea-level cycles. In general, model results 36 demonstrate the importance of the dynamics of the fluvial surface on the system response under 37 38 a large range of input parameter values. Specifically, model results suggest that time lags in the ABT response during sea-level cycles can result in geologically long-lived river incision in the 39 upper and mid portions of the fluvial surface during sea-level rise. These results suggest that the 40 41 relationship between the coastal onlap configuration of strata and relative changes in sea level is complex, and therefore not necessarily a good indicator of contemporaneous sea-level changes. 42

<u>Keywords</u>: Enthalpy method, Fluvial deltas, sea-level cycles, Alluvial-basement transition,
Shoreline, river incision

46 **1. Introduction**

Fluvial deltas are composites of several basic environments, including a depositional fluvial 47 region and a subaqueous offshore region, that generally resemble a triangular prism 48 superimposed upon a relatively planar basement profile (Figure 1a; Chavarrías et al., 2018; 49 Lorenzo-Trueba et al., 2009; Paola, 2000; Posamentier et al., 1992; Swenson et al., 2005). This 50 triangular sedimentary prism presents three geomorphic boundaries or vertices: the alluvial-51 bedrock transition (ABT), which separates the bedrock (or basement) from the depositional 52 53 fluvial region, the shoreline (SH), which separates the fluvial region from the subaqueous depositional region, and the delta toe where the subaqueous sediment wedge intersects with the 54 basement. Changes in the length of the depositional fluvial domain occur via transgression (i.e., 55 56 SH landwards migration), regression (i.e., SH seawards migration), coastal onlap (i.e., ABT landwards migration), and coastal offlap (i.e., ABT seawards migration) (see Figure 1). These 57 changes are in general a function of the sediment supply to the sedimentary prism, the efficacy of 58 the sediment transport and deposition along the fluvial surface, and relative sea-level variations 59 (i.e., the combination of eustatic sea level changes and subsidence). For instance, if sediment 60 supply is high relative to both the length of the fluvial surface and the accommodation created by 61 62 sea-level rise, the results is SH regression and coastal onlap, which causes an overall lengthening of the sedimentary prism, as well as an increase in elevation (i.e., river aggradation) of the fluvial 63 64 surface (Figure 1b). A combination of relative sea-level fall with low sediment supply, however, typically results in regression, coastal offlap, and a decrease in elevation (i.e., river degradation) 65 of the fluvial surface (Figure 1c). Additionally, Muto and Steel (2002) found that a low sediment 66

supply relative to the length of the fluvial surface and the rate of relative sea-level rise can lead
to a break in the triangular geometry of the sedimentary prism as the system transgresses (Figure
1d).

70

Cycles of SH transgression/regression and coastal onlap/offlap in the sedimentary record (Figure 71 72 1) can potentially allow for reconstruction of a basin's history of sediment supply and paleo-sea level (Henriksen et al., 2009; Törnqvist et al., 2006). To tackle this inverse problem, the 73 migration of the internal boundaries that describe the evolution of the system (e.g., ABT, SH) 74 75 have to be computed as a part of the solution to the overall geological problem (Lorenzo-Trueba et al., 2013, 2009; Lorenzo-Trueba and Voller, 2010; Marr et al., 2000; Swenson et al., 2000). 76 Analogous to the migration of the ice/water front in a one phase Stefan melting problem (Crank, 77 1984), Swenson et al. (2000) applied this framework to the migration of the SH in sedimentary 78 basins. In particular, these authors used an analogy between heat and sediment diffusive 79 transport to describe the movement of the SH under varying conditions of sediment supply and 80 relative sea level. Follow-up work by Voller et al. (2004) found that in the particular case of 81 constant sediment supply and a fixed sea level, the problem presented by Swenson et al. (2000) 82 83 allows for a closed-form analytical solution. Based on Voller et al. (2004), Capart et al. (2007), and Lai and Capart (2007) developed analytical solutions in which the ABT and the SH were 84 treated as independent moving boundaries. Lorenzo-Trueba et al. (2009) expanded on this work 85 86 by developing an analytical solution able to track both the ABT and the SH under conditions of constant sediment supply and fixed sea-level. Lorenzo-Trueba et al. (2009) also validated this 87 solution against flume experiments under a range of system parameters. In addition to studying 88 89 the kinematics of ocean shoreline deltas, similar models and solution methodologies along the

90 lines of those noted above, have also been applied in studies of lake deltas and morphology, e.g.,91 (Capart et al., 2010).

92

Although simplified solutions can increase the clarity and insights the model facilitates, moving 93 boundary problems only have analytical solutions in a limited range of scenarios. In order to 94 95 study more general cases, different numerical methods have been developed for the dual ABT and SH moving boundary problem (Lorenzo-Trueba and Voller, 2010; Parker et al., 2008; Voller 96 et al., 2006). Parker et al. (2008) developed a deforming grid method, based on a Landau front-97 98 fixing approach, able to track both the ABT and the SH under constant sea-level rise in a onedimensional setting. A drawback of the deforming grid method, however, is that the extension to 99 two-dimensions is far from straightforward. Voller et al. (2006) developed a solution based on 100 101 the enthalpy method, able to operate on a fixed grid under constant sea level, and focused on the dynamics of the SH. Lorenzo-Trueba and Voller (2010) extended this numerical solution to 102 account for the migration of both the ABT and SH. Despite these recent developments, however, 103 to date all numerical solutions had been restricted to either a fixed sea level or constant sea-level 104 rise scenarios. The only attempt to solve the problem under sea-level cycles was by Lorenzo-105 106 Trueba et al. (2013), who developed an integral approximation of the Exner equation assuming a quadratic fluvial surface profile. This solution, however, is not able to account for full cycles of 107 transgression and regression (only cases where transgression follows regression). Thus, our first 108 109 goal is to extend the enthalpy-like numerical solution from Lorenzo-Trueba and Voller (2010) to account for sea-level cycles, as well as cycles of SH transgression/regression. Second, we 110 111 investigate potential modes of coastal behavior under sea-level cycles and a wide range of 112 system parameters.

114 **2. The Dual Moving Boundary Problem**

115 2.1 Equations

116

We model fluvio-deltaic evolution in cross-section as described in Figure 2a. As opposed to 117 previous modeling efforts that account for different shoreface morphologies (Lai and Capart, 118 119 2007; Swenson et al., 2005), temporal changes in sediment supply (An et al., 2017), or breaks in the basement slope (Lai et al., 2017), we assume a linear basement slope β , a linear foreset slope 120 ψ , and a steady sediment supply q_0 . We adopt this idealized cross-shore geometry to simplify the 121 calculations and focus on the role of the fluvial surface dynamics on the response of the system. 122 Given such cross-shore geometry (Figure 2), the evolution of the fluvio-deltaic system can be 123 described in terms of the locations of the ABT (x = r(t)), the SH (x = s(t)), and the delta toe 124 (x = w(t)). In the absence of differential subsidence, we can describe changes in the elevation h 125 at any location of the fluvial surface with respect to current sea level (Figure 2a) as the 126 divergence of the sediment flux q (Paola and Voller, 2005), 127

128
$$\frac{\partial h}{\partial t} = -\frac{\partial q}{\partial x}, \quad r(t) \le x \le s(t)$$
 (1)

where x is positive in the seaward direction, and x=0 is located at the intersection between the initial sea level and the basement.

131 Following numerous efforts, which include both numerical modeling and laboratory experiments

132 (Paola et al., 1992; Ribberink and van der Sande, 1985; Fagherazzi and Overeem, 2007; Parker

- and Muto, 2003; Postma et al., 2008; Swenson et al., 2000; Swenson and Muto, 2007), we
- assume that q is primarily controlled by the fluvial slope. In particular, for simplicity we assume

that q is linearly related to the fluvial slope as follows (Paola et al., 1992; Lorenzo-Trueba et al.,
2013; Lorenzo-Trueba and Voller, 2010; Marr et al., 2000; Swenson et al., 2000; Swenson and
Muto, 2007)

138
$$q(x) = -v \frac{\partial h}{\partial x}$$
 (2)

where v is the 'fluvial diffusivity', which can be calculated as a function of water discharge andgrain size characteristics (Paola, 2000).

141

The combination of equations (1) and (2) leads to the so-called linear diffusion equation, which generally requires two boundary conditions and an initial condition to be solved. In this case, however, the locations of the ABT and the SH (i.e., *r* and *s*) are unknown a priori and need to be solved as part of the solution. Consequently, the problem requires four boundary conditions instead of just two. The first condition matches the fluvial surface elevation at the ABT to the basement elevation:

$$148 h|_{x=r} = -\beta r (3a)$$

149 The second condition implies that the elevation of the fluvial surface at the SH is equal to sea150 level:

$$151 h|_{x=s} = Z (3b)$$

where Z is the sea level. The third condition imposes a given sediment input q_0 at the ABT:

153
$$-v\frac{\partial h}{\partial x}\Big|_{x=r} = q_0 \tag{3c}$$

154 The fourth condition in general relates the sediment flux that reaches the SH with the rate of migration of the foreset toe, which is defined as $dw/dt = ds/dt + 1/\psi \cdot dZ/dt$ (Swenson et 155 156 al., 2000). In the particular case in which the shoreface toe only migrates seawards (i.e., dw/dt > 0), the system maintains the wedge geometry depicted in Figure 1, and we can define 157 the basin depth as $D(x,t) = \psi/(\psi - \beta) \cdot (s\beta + Z)$ (Lorenzo-Trueba et al., 2013). For 158 159 simplicity, however, given that the foreset slope ψ is generally orders of magnitude larger than any other slope in the system, including the basement slope β , we assume $\psi/(\psi - \beta) \sim 1$ 160 (Edmonds et al., 2011; Lorenzo-Trueba et al., 2013, 2009; Lorenzo-Trueba and Voller, 2010; 161 Swenson and Muto, 2007). This assumption implies that a shift from regression to transgression 162 coincides with the abandonment of the subaqueous foreset, which means that the SH and the 163 delta toe always migrate in the same direction (i.e., dw/dt = ds/dt). In this scenario, the fourth 164 165 boundary relates the sediment flux that reaches the SH with the rate of migration of the SH and the ocean depth as follows: 166

167
$$-v\frac{\partial h}{\partial x}\Big|_{x=s} = \begin{cases} D(x,t)\frac{ds}{dt}, & \frac{ds}{dt} > 0\\ 0, & \frac{ds}{dt} \le 0 \end{cases}$$
(3d)

168 When the SH migrates seawards (i.e., ds/dt > 0) beyond past SH locations, the system 169 maintains the wedge geometry and the basin depth reduces to $D(x, t) = s\beta + Z$. In contrast, 170 when all sediments deposit on the fluvial surface before reaching the SH, the SH sediment flux is 171 equal to zero and the SH migrates landwards (i.e., $ds/dt \le 0$). Under this condition, the SH 172 detaches from the subaqueous foreset (Figure 2b), a condition previously defined as 'autobreak' 173 (Muto and Steel, 2002). Additionally, in some instances the SH migrates seaward (i.e., ds/dt > 174 0) over subaqueous deposits left during autobreak, in which case D(x, t) corresponds to the 175 ocean depth of these offshore deposits (Figure 2c).

176 Under these conditions, with equations (1-3) and a given initial geometry: s(0) = r(0) = 0, we

177 can fully describe the dynamics of the fluvial surface under sea-level changes, including cycles

178 of regression and transgression (Figure 2).

179

180 2.2 A dimensionless form

181 In this section, we reduce the number of controlling parameters to a minimum by rewriting the 182 governing equations (1-3) in dimensionless form. The scaling used towards this end is as follows

183
$$x^{d} = \frac{x}{l}, t^{d} = \frac{t}{\tau}, s^{d} = \frac{s}{l}, r^{d} = \frac{r}{l}, Z^{d} = \frac{Z}{l\beta}, h^{d} = \frac{h}{l\beta}, D^{d} = \frac{D}{l\beta}, q^{d} = \frac{q\tau}{l^{2}\beta}$$
 (4)

where *l* is the horizontal scale (e.g., a characteristic delta length), $l\beta$ is the vertical scale, and $\tau = l^2/v$ is an 'equilibrium timescale' defined by Paola et al. (1992). From the scaling in (4), we obtain one dimensionless group: the ratio of the fluvial to the bedrock slope at the ABT

187
$$R_{ab} = -\frac{1}{\beta} \frac{\partial h}{\partial x}\Big|_{x=r} = \frac{q_0}{\beta v}$$
(5)

188 which is physically constrained within the range $0 < R_{ab} < 1$.

189 Dropping the *d* superscript for convenience of notation, the

190 dimensionless versions of equations (1) to (3) become:

191
$$\frac{\partial h}{\partial t} = \frac{\partial^2 h}{\partial x^2}, \quad r(t) \le x \le s(t)$$
 (6)

192 with conditions

193
$$h|_{x=r} = -r$$
 (7a)

$$194 h|_{x=s} = Z (7b)$$

195
$$-\frac{\partial h}{\partial x}\Big|_{x=r} = R_{ab}$$
(7c)

196
$$-\frac{\partial h}{\partial x}\Big|_{x=s} = \begin{cases} D(x,t)\frac{ds}{dt}, & \frac{ds}{dt} > 0\\ 0, & \frac{ds}{dt} \le 0 \end{cases}.$$
 (7d)

197 The initial conditions are:

198
$$s(t=0) = r(t=0) = 0.$$
 (8)

In the particular case in which the SH only migrates seawards (i.e., ds/dt > 0), the system maintains the wedge geometry depicted in Figures 1a and 2a, and we can define the basin depth as D(x, t) = s + Z (Lorenzo-Trueba et al., 2013). Under this special case, equations (6) – (8) admit close form analytical solutions, which are described in section 4. In general, however, these equations require a numerical solution.

204

3. The Geomorphic Enthalpy Method

In this section, we develop a numerical solution able to operate in cases where the closed form solutions do not hold. Moreover, the objective of this section is to present a fixed grid enthalpylike method that solves the problem numerically without the need of tracking the ABT and the SH as part of the solution (Voller et al. 2006; Lorenzo-Trueba and Voller 2010). With this objective in mind, we define the enthalpy function H(x, t), which in our case represents the sediment prism thickness (Figure 3), as follows:

212
$$H(x,t) = h(x,t) + Z(t) - E(x)$$
 (9)

where E(x) denotes the basement elevation, i.e., E(x) = -x. Inverting (9), we can describe the elevation respect to current sea level (Figure 2a) anywhere in the domain as follows

215
$$h = \max(H + E - Z, 0)$$
. (10)

As defined by equation (10), *h* is always greater than zero landward of the SH, and zero seawards of the SH (Figure 3). Consequently, sediment fluxes as described in equation (2) are zero beyond the SH, which implies that the subaqueous portion of the fluvial-delta maintains its sediment thickness and hence its shape. Although we believe this is a reasonable assumption to first order, future versions of the model will investigate the effect of waves and tides on the transport of sediments in the subaqueous portion.

Equations (9) and (10) are fully consistent with the original enthalpy formulation introduced by Crank (1984). However, as previously noted by Voller et al. (2006) and Lorenzo-Trueba and Voller (2010), in this case the term representing the latent heat L(x, t) = Z(t) - E(x) can be a function of space and time. Using equations (9) and (10), we can then describe the problem using the same sediment balance equation for the full solution space, i.e.,

227
$$\frac{\partial H}{\partial t} = -\frac{\partial q}{\partial x}, \quad -\infty \le x \le \infty$$
 (11)

where *q* is the sediment flux described in equation (2). At the upstream limit of the domain, the sediment flux is always equal to the sediment input, which in dimensionless numbers is equal to R_{ab} , i.e., $\lim_{x\to\infty} q = R_{ab}$. At the downstream limit of the domain, the elevation above sea level is always equal to zero, i.e., $\lim_{x\to\infty} h = 0$. Equation (11) also requires initial conditions to be solved, which we define as follows

233
$$H(x,0) = 0$$
 (12a)

234
$$h(x,0) = \begin{cases} -x, & x < 0\\ 0, & x \ge 0 \end{cases}$$
 (12b)

We develop a numerical solution for equations (9) to (12) based on a uniform grid size Δx and time step size Δt . We set the origin point x = 0, where the ABT and SH are located initially, at the interface between two nodes in the center of the domain (Figure 4). We set the index *i* for the first node landward of the origin to be equal to zero. The value of *i* increases as we move seaward, and decreases and becomes negative as we move landwards. In general, we can express the location of node *i* as $x_i = (i - 0.5) \cdot \Delta x$.

241 We discretize equation (11) at node *i* using the following finite differences form

242
$$H_{i,j+1} = H_{i,j} + \frac{\Delta t}{\Delta x} \cdot \left(q_{i+\frac{1}{2},j} - q_{i-\frac{1}{2},j} \right)$$
(13)

where the superscript *j* refers to the time step, and the subscript i+1/2 refers to the interface between nodes *i* and i+1. This equation guarantees that sediment is conserved in every node of the entire domain. Additionally, we compute the flux from node *i* to node i+1 at time step *j* as

246
$$q_{i+\frac{1}{2},j} = \min\left(H_{i,j}\frac{\Delta x}{\Delta t} + q_{i-\frac{1}{2},j}, \frac{h_{i,j}-h_{i+1,j}}{\Delta x}\right).$$
 (14)

247 We note that the formulation introduced by equation (14) departs from the formulation

- introduced by Lorenzo-Trueba and Voller (2010) (i.e., $q_{i+\frac{1}{2},j} = \min(R_{ab}, (h_{i,j} h_{i+1,j})/\Delta x)).$
- 249 Lorenzo-Trueba and Voller's formulation only works when the ABT solely migrates landwards
- and sediment deposition takes place along the fluvial surface on every cell and time step.
- 251 Consequently, in this particular scenario sediment flux q is bounded above by the upstream

sediment supply in dimensionless form (i.e., $q \le R_{ab}$). In the more general case presented here, however, we can simulate sediment erosion on the fluvial surface, as well as seaward migration of the ABT. In this case, under the assumption of a non-erodible basement, sediment flux $q_{i+\frac{1}{2}j}$ is bounded above by the sum of the sediment input to the upstream cell $q_{i-\frac{1}{2}j}$ and the total sediment volume in the upstream cell $H_{i,j}\Delta x/\Delta t$.

In order to guarantee stability, the time and space steps need to satisfy $\Delta t / \Delta x^2 < 0.5$. To meet

this stability criterion, we generally use a space step $\Delta x = 0.01$ and a time step in the

range $10^{-5} \le \Delta t \le 5 \cdot 10^{-5}$. Higher resolution may be needed to ensure accuracy for high

260 values of R_{ab} .

At each time step, the solution of (13) explicitly provides new values for the sediment

thickness $H_{i,j+1}$ at each node. We then calculate the values at the new time step for the sediment

heights $h_{i,j+1}$ from the discrete form of equation (12). With this information, we can calculate

the sediment fluxes using equation (14), and move to the next time step to solve again equation(13).

Additionally, although not required, we can determine the position of the ABT at each time step by searching left to right through the domain and finding the first cell *i* where $q_{i-\frac{1}{2},j} \neq q_{i+\frac{1}{2},j}$. This cell represents the most landward location where sediment deposition occurs, i.e., the cell immediately seaward of the ABT. We then estimate the ABT position by interpolating between nodes *i* and *i* – 1 as follows:

271
$$r_j = \frac{h_{i,j} + Z_j + R_{ab} x_i}{1 - R_{ab}}.$$
 (15)

We can also estimate the location of the SH at each time step. Under SH progradation, the current total sediment field $H_{i,j}$ is searched, and the first node *i* where $0 < H_{i,j} + E_i < Z_j$ is located. The SH position is then determined by interpolation through the control volume around node *i*, i.e.

276
$$s_j = (i-1)\Delta x - \frac{H_{i,j}}{E_i - Z_j}\Delta x$$
. (16)

277

278 **4. Verification of the enthalpy method**

279 We verify the proposed model under two sea-level change scenarios that admit closed form 280 analytical solutions: square-root sea-level rise and fall, and constant sea-level rise. Under the condition of sea-level change proportional to the square root of time i.e., $Z = 2\lambda_z \sqrt{t}$, Lorenzo-281 Trueba et al. (2013) developed an analytical similarity solution in which the movements of the 282 ABT and SH are given by equations of the form: $r = -2\lambda_{ab}\sqrt{t}$ and $s = 2\lambda_{sh}\sqrt{t}$, where λ_{ab} and 283 λ_{sh} are constants determined through the solution of two algebraic equations (Lorenzo-Trueba et 284 al., 2013). We use this analytical solution to assess accuracy of the enthalpy method under a 285 wide range of λ_z and R_{ab} scenarios (see Appendix). In this section, we present two examples that 286 demonstrate model performance under both ABT seaward and landward migration, including 287 their profile evolution (Figure 5). 288

289

Under a constant sea-level rise rate \dot{z} (i.e., sea level is described as $Z = \dot{z} \cdot t$), the system eventually reaches a point at which all incoming sediment deposit on the fluvial surface in order to keep pace with sea-level rise (Muto, 2001; Parker and Muto, 2003), which results in the fluvial plain abandoning the foreset or submarine portion (Figure 2b). When this happens, the 294 system first enters a transition period in which the length of the fluvial plain increases and both the ABT and the SH migrate landwards. This transition period ends when the fluvial surface 295 attains a fixed geometry, and both the ABT and the SH attain a constant landward migration rate. 296 At this point, the geometry of the fluvial surface, as well as the ABT and SH trajectories, can be 297 described analytically (a full derivation of this solution is included in the Appendix). We use this 298 analytical solution to test the fixed grid numerical scheme for a wide range of R_{ab} and \dot{z} values. 299 In all scenarios, there is agreement between the analytical and numerical solutions (see 300 Appendix). 301

302

5. System response to sea-level cycles: The importance of fluvial surface dynamics 303 Numerous studies over the past few decades present sea-level change as the most important 304 allogenic (i.e., external) forcing affecting coastal areas such as fluvial deltas and coastal margins 305 (Blum et al., 2013; Catuneanu et al., 2009; Van Wagoner et al., 1990; Van Wagoner and 306 Bertram, 1995), and consequently as the primary control on stratigraphic architecture. While 307 308 evidence for incised (paleo) valley systems formed during oscillations in sea level during the Quaternary is extensive (Blum et al., 2013; Blum and Törnqvist, 2000), the range of sea-level 309 310 cycle amplitudes and frequencies stored in the stratigraphic record remains unclear (Li et al., 311 2016). In this section, we demonstrate how the proposed enthalpy method can be used to bring some light to this question by exploring the dynamics and stratigraphy of the system under sea-312 level variations. In particular, we go beyond the scenarios investigated in the model verification 313 and explore the system response under sinusoidal sea-level cycles, i.e., 314

 $315 \quad Z = A\sin(B \cdot t) \tag{17}$

316 where A and B are the dimensionless amplitude and frequency (i.e., 1/period) of the sea-level cycles. We select a representative length scale l = 100 km, a basement slope $\beta = 10^{-3}$, and a 317 diffusivity $v = 10^5 \text{m}^2 \text{y}^{-1}$ associated with a catchment length of ~100 km (Swenson et al., 2000). 318 319 In this way, we can use the dimensional scaling described in equation (4) to calculate the 320 amplitude and period of sea-level cycles using the A and B values. For instance, A=1 and B=1correspond to sea-level cycles of 100m in amplitude and a period of 100,000 years, which are 321 322 comparable to quaternary-scale eccentricity-driven eustatic sea level cycles (Hajek and Straub, 323 2017). Lower A and B values (e.g., A=0.3 and B=0.4) better match with late Miocene conditions, when obliquity cycles (~ 40 ky) resulted in sea changes with ranges of 10–35 m. 324

325

326 An interesting feature under sea-level cycles is that the SH can reverse its direction of migration. During these reversals, the geometric configuration of the system shifts between the one shown 327 328 in Figure 2a, in which wedge geometry is maintained, and Figure 2b, in which the foreset and the 329 fluvial plain abandons the submarine portion (i.e., autobreak). This is well illustrated in Figures 6 330 and 7, which demonstrate that the geomorphic enthalpy method introduced here can account for 331 transgression followed by regression and vice versa. Figure 6 includes three stratigraphic profiles produced by the model that demonstrate the effect of R_{ab} on the system response. As we 332 increase R_{ab} , which is proportional to the sediment supply (see equation (5)), the magnitude and 333 occurrence of river incision (i.e., ABT seaward migration) and SH transgression are reduced, and 334 there is larger preservation of sedimentary deposits. The formation and evolution of each of these 335 stratigraphic profiles is included in the supplementary material, and Figure 7a includes the ABT 336 and SH trajectories for the scenario depicted in Figure 6c (medium R_{ab} value). 337

Figures 6 and 7 (and videos in the supplementary material) also illustrate the importance of the 339 dynamics of the fluvial surface on the ABT and SH responses. During the sea-level rise phase, 340 the relief of the fluvial surface decreases and its convexity increases as a large fraction of the 341 sediment input deposits on the subaerial portion of the sedimentary prism. In contrast, under sea-342 level fall the relief and concavity of the fluvial surface increase as a larger fraction of sediments 343 344 bypass the subaerial portion of the delta to build the foreset. These shifts in the curvature and relief of the fluvial surface can delay the response of the system to sea-level variations. In 345 particular, the transition from a concave and seaward migrating fluvial surface profile during sea-346 347 level fall to a convex and lower relief fluvial surface during the sea-level rise can result in river incision during the sea-level rise (Figures 6-7a); Lorenzo-Trueba et al. (2013) first reported this 348 interesting phenomenon. Additionally, the transition from a convex fluvial surface profile during 349 the sea-level rise stage to a concave profile during the sea-level fall stage can result in the 350 truncation of sediment layers in the nearshore region, leaving 'lenses' of older sediment 351 surrounded by newer sediments (Figure 6). It is important to note that neither of these two 352 behaviors can be captured by models that impose a linear fluvial slope (Kim and Muto, 2007; 353 Lorenzo-Trueba et al., 2012), or the general sequence stratigraphic model, which assumes a fixed 354 355 fluvial surface profile that translates seaward and landward, tracking the regressing and transgressing SH (Posamentier and Vail, 1988). 356

357

To further explore the time lags in system response, we define the ABT and SH residuals (i.e., s_{res} and r_{res}) as the difference between the ABT and SH trajectories under sea-level cycles and the corresponding trajectories under constant sea level (Figure 7a). By plotting the residual trajectories with the sea-level curve (Figure 7b and 7c), we find that SH response is typically in 362 phase with sea level such that maxima and minima in the SH trajectory correspond approximately to minima and maxima in sea level, respectively. In contrast, delays in the ABT 363 response to sea-level variations can be geologically long-lived, and can result in river incision 364 that prolongs into the sea-level rise stage (Figure 8 and 9). Such time delays increase as R_{ab} 365 increases, and can reach values of hundreds of thousands of years, but barely change as a 366 367 function of the amplitude of the sea-level oscillations A (Figure 8a). River incision during sealevel rise, however, can only occur when A is at least large enough to cause river incision during 368 the fall stage, which can then extend into the sea-level rise stage. Thus, the total sediment 369 370 volume eroded (i.e., river incision) under sea-level rise increases as A increases (Figure 8b), and represents a significant fraction of the total sedimentary wedge volume under high amplitude 371 sea-level oscillations (Figure 9). 372

373

The relationship between the sediment volume eroded during sea-level rise and R_{ab} is more 374 375 complex (Figure 8b). Under low to medium values of R_{ab} , the seaward migration of the ABT drives river incision (Figure 9b and 9c). In this case, as R_{ab} increases, the longer the seaward 376 377 migration of the ABT prolongs beyond the sea-level fall stage into the sea-level rise stage, which in turn results in a higher sediment volume eroded. Under medium to high values of R_{ab} , 378 however, the ABT can maintain its landward migration even under extended periods of sea-level 379 380 fall, and river incision occurs instead due to curvature changes of the fluvial surface (Figure 9d). 381 In this scenario, an increase in R_{ab} , which is proportional to the sediment supply (see equation (5)), tends to reduce the sediment volume eroded under sea-level cycles. 382

383

384 **6. Discussion and future work**

385 Numerous field, experimental, and theoretical studies have been conducted to date to understand how allogenic controls such as sea-level change influence stratigraphy (Allen, 1978; Armitage et 386 al., 2011; Heller et al., 2001; Heller and Paola, 1996; Hickson et al., 2005; Martin et al., 2011, 387 2009; van Heijst and Postmal, 2001; Van Wagoner et al., 1990). Despite all these efforts, which 388 provide a sound conceptual framework for interpreting ancient deposits, there exist fundamental 389 390 gaps regarding the relationship between processes, stratigraphy, and fluvial-deltaic evolution. In this manuscript, we address this knowledge gap by developing and verifying a fixed grid 391 enthalpy-like numerical solution aimed to explore the evolution of fluvial deltas under a wide 392 393 range of scenarios. The novelty of this modeling framework, which can be viewed as a generalized one-dimensional Stefan problem with two geomorphic moving boundaries (i.e., the 394 ABT and the SH), is that the "latent heat" (which resembles ocean depth in our case) can change 395 both in time and space. As a result, this model can for the first time incorporate sea-level cycles, 396 as well as cycles of SH transgression/regression. 397

398

Model results in this manuscript do not aim at specifically reproducing the evolution of any 399 particular fluvial delta, and therefore do not capture the complexities associated with multiple 400 401 grain sizes, sediment compaction, or deep crustal processes. The model also assumes that the evolution of the system can be described in a one-dimensional longitudinal section, leaving out 402 processes such as river avulsions, which can play a role on the large-scale evolution of the 403 404 system. These model simplifications, however, allow us to focus our analysis on the interplay between sediment supply, sea-level changes, and the dynamics of the fluvial surface. 405 406 Additionally, given the simplicity of the model we can explore the effect of this interplay under a wide range of system parameters. 407

Overall, model results demonstrate the potential of numerical heat transfer methods, specifically 409 those developed to solve moving boundary problems, to advance our understanding of the 410 formation and evolution of sedimentary basins. Model results also demonstrate that the dynamics 411 of the fluvial surface can play an essential role on the system response to sea-level variations. 412 Previous studies have highlighted the importance of autogenic storage and release processes 413 during a full sea-level cycle, such that periods of sea-level rise are not purely depositional while 414 periods of sea-level fall are also not purely erosional (Blum and Price, 1998; Holbrook, 2001; 415 416 Strong and Paola, 2008). To the best of our knowledge, however, this is the first study that relates changes in the relief and concavity of the fluvial surface profile during sea-level cycles 417 with the occurrence of geologically long-lived (i.e., thousands of years) river incision during sea-418 level rise. Moreover, the model predicts that the volume of sediment eroded during river incision 419 under sea-level rise significantly increases as the amplitude of the sea-level oscillations increase. 420 Future work will aim at narrowing down the conditions and past sea-level changes that could 421 make such behavior likely. Additionally, we are planning to carry out laboratory-scale flume 422 experiments to validate the model results. The next step in terms of numerical modeling will be 423 424 to extend the geomorphic enthalpy model into two dimensions.

425

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comments.

432	Computer Code Availability	
433	The code "1D enthalpy method", developed by William Anderson and Jorge Lorenzo-Trueba	
434	can be accessed since October 2018 at https://github.com/JorgeMSU/1D-enthalpy-method. For	
435	details about this code, contact Jorge Lorenzo-Trueba via email (lorenzotruej@montclair.edu) or	
436	by phone (973-655-5320). Jorge Lorenzo-Trueba's office is at 1 Normal ave., Motntclair State	
437	University, NJ 07043. The code is less than 200 lines, it can run in a standard laptop, and is	
438	written in matlab.	
439		
440		
441	Appendix A: Additional verification of the enthalpy method.	
442	In this section, we include further testing of the fixed grid numerical scheme under two sea-level	
443	change scenarios that admit closed form analytical solutions: square-root sea-level rise and fall,	
444	and constant sea-level rise.	
445		
446	A.1 Square-root sea-level rise and fall	
447		
448	Under the condition of sea-level change proportional to the square root of time i.e., $Z = 2\lambda_z \sqrt{t}$,	
449	Lorenzo-Trueba et al. (2013) developed an analytical similarity solution in which the movements	
450	of the ABT and SH are given by equations of the form:	
451	$r = -2\lambda_{ab}\sqrt{t} \tag{A1a}$	

$$452 s = 2\lambda_{sh}\sqrt{t} (A1b)$$

where λ_{ab} and λ_{sh} are constants determined through the solution of two algebraic equations 453 454 (Lorenzo-Trueba et al., 2013). We use this analytical solution to assess accuracy of the enthalpy method under a wide range of R_{ab} and λ_Z values. Figure 5 shows plots of the SH and ABT 455 trajectories over time for two values of R_{ab} during sea-level fall. In both scenarios, there is 456 agreement between the analytical and numerical solutions. Depending on both R_{ab} and the value 457 of λ_Z the delta can undergo coastal offlap or coastal onlap during sea-level fall. The profile 458 evolutions in figure 5 illustrate differences in concavity of the fluvial surface that are a result of 459 460 the direction of ABT migration. In scenarios of sea-level fall proportional to the square root of time larger values of R_{ab} or smaller values of λ_Z result in coastal onlap and a concave up fluvial 461 surface. However, significantly decreasing R_{ab} or increasing the magnitude of λ_Z causes the 462 delta to undergo coastal offlap and produces a concave down fluvial surface. During costal offlap 463 464 sediments are reworked in the upstream portion of the delta and provided to the rest of the system causing sediment flux values in the fluvial surface to exceed R_{ab} and resulting in the 465 concave downward profile. Model runs for several values of R_{ab} and λ_Z are included in figures 466 A1 and A2. 467

A further test of the robustness of the enthalpy solution is revealed by investigating its 468 performance across the entire feasible range of the ABT slope ratio $0 < R_{ab} < 1$; in each case 469 the value of λ_Z is set proportional to λ_{sh} . First, the analytical solution in Lorenzo-Trueba et al. 470 2012 is used to predict values of λ_{ab} and λ_{sh} . Then, we extract the values of λ_{ab} and λ_{sh} at 471 specific values of $R_{ab}[0.05: 0.05: 0.95]$ through fitting the forms in (9) to the predicted 472 473 trajectories r and s given by the enthalpy solution. Benchmarks are made for both a sea-level rise (e.g., $\lambda_Z = 0.5\lambda_{sh}$) and a sea-level fall (e.g., $\lambda_Z = -0.5\lambda_{sh}$). In Figure A3 we present a 474 comparison of the analytical values of the moving boundary parameters (solid-line) with those 475

predicted by the enthalpy method (shapes). We find that across a wide range of conditions thetime stepping solution matches the analytical solution.

478

479 A.2 <u>Constant sea-level rise</u>

480

Under a constant sea-level rise rate \dot{z} (i.e., sea level is described as $Z = \dot{z} \cdot t$), the system can 481 reach a point in which the incoming sediment flux is insufficient to supply the foreset (Muto, 482 2001; Parker and Muto, 2003), which results in the fluvial plain abandoning the submarine 483 portion (Figure 2b). When this happens, the system first enters a transition period in which the 484 length of the fluvial plain increases and both the ABT and the SH migrate landwards. This 485 transition period ends when the fluvial surface attains a fixed geometry, and both the ABT and 486 the SH attain a constant landward migration rate. At this point, the problem admits an analytical 487 solution as the fluvial-surface attains a fixed geometry that migrates landwards at a given speed. 488 489 We can then describe such analytical solution by setting the following similarity variable: $\xi = x + \dot{z}t,$ (A2a) 490

491 scale the sediment height by

492
$$\eta = h - \dot{z}t,$$
 (A2b)

and define the following location for the boundaries of the fluvial surface

$$494 s^* = s_i - \dot{z}t (A3a)$$

495
$$r^* = r_i - \dot{z}t$$
. (A3b)

496 In this way, the similarity solution becomes

497
$$\frac{d^2\eta}{d\xi^2} - \dot{z}\frac{d\eta}{d\xi} - \dot{z} = 0, \qquad r^* \le \xi \le s^*$$
(A4)

498 with boundary conditions

499
$$\eta|_{\xi=s^*} = 0$$
 (A5a)

500
$$\eta|_{\xi=r^*} = -r^*$$
 (A5b)

501
$$\left. \frac{\partial \eta}{\partial \xi} \right|_{\xi = r^*} = -R_{ab}$$
 (A5c)

502
$$\left. \frac{\partial \eta}{\partial \xi} \right|_{\xi = s^*} = 0$$
. (A5d)

503 On satisfying (A3), (A4a), and (A4d) we obtain the following solution

504
$$\eta = \frac{1}{\dot{z}} \exp(\dot{z}\xi - \dot{z}s^*) - \xi + \frac{R_{ab} - 1}{\dot{z}}$$
 (A6a)

505
$$h = \frac{1}{\dot{z}} \exp(\dot{z}x - \dot{z}s) - x + \frac{R_{ab} - 1}{\dot{z}}.$$
 (A6b)

506 From (2) and (3) we obtain the values of s^* , and r^*

$$507 s^* = \frac{R_{ab}}{\dot{z}} (A7a)$$

508
$$r^* = \frac{1}{\dot{z}} [R_{ab} + \ln(1 - R_{ab})].$$
 (A7b)

509 Thus, the length of the fluvial surface can be calculated as

510
$$s^* - r^* = s_i - r_i = \frac{\ln(1 - R_{ab})}{\dot{z}}.$$
 (A8)

511 We use this analytical solution to test the fixed grid numerical scheme for a wide range of 512 R_{ab} and \dot{Z} values. Figure A4 shows plots of the movement of the SH and ABT over time. We

513	find that the trajectories predicted by the enthalpy solution (solid-lines) eventually match the
514	analytical solution (dashed-line).

- 515 Additionally, further test of the robustness of the enthalpy solution is revealed by investigating
- its performance across the entire feasible range of the ABT slope ratio $0 < R_{ab} < 1$. In
- 517 particular, we calculate the length of the fluvial surface at steady state (i.e., *s*-*r*) for specific
- values of R_{ab} [0.05: 0.05: 0.95], using the enthalpy solution and the analytical solution (equation
- 519 (A7)). In Figure A5 we present a comparison of the analytical values of the moving boundary
- 520 parameters (solid-line) with those predicted by the enthalpy method (shapes). We find that across
- a wide range of conditions the time stepping solution matches the analytical solution.
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686 Tables

687 Table 1. State Variables and their Dimensions

Symbol	Units	Description	Dimensionless
			symbol
t	Т	Time	t
x	L	Horizontal distance	x
h	L	Height above current sea-level	h
r	L	Alluvial-bedrock transition horizontal distance from origin	r
S	L	Shoreline horizontal distance from origin	S
<i>q</i>	$L^2 \cdot T^{-1}$	Sediment flux	<i>q</i>
Ζ	L	Sea-level	Ζ
H	-	Enthalpy	Н
E	L	Basement elevation	Ε

Table 2. Description of the input parameters and their dimensionless groups

Symbol	Units	Description	Dimensionless symbol
<i>q</i> ₀	$L^2 \cdot T^{-1}$	Sediment flux at ABT	
v	$L^2 \cdot T^{-1}$	Fluvial diffusivity	R_{ab}
β	-	Basement slope	

Ψ	-	Foreset slope	R _{sh}
Ż	L·T ⁻¹	Rate of sea-level rise	Ż
A	L	Amplitude of sea-level oscillations	А
В	T-1	Frequency of sea-level oscillations	В

692 Figures



693

Figure 1. Conceptual sketches of the fluvio-deltaic system illustrating (a) geomorphic moving
boundaries and key components, and (b)-(d) shoreline regression/transgression, coastal
onlap/offlap at the ABT, and river aggradation/incision. Note the strong exaggeration of the
vertical scale.



Figure 2. (a) Model setup, including state variables. (b) Sketch for autobreak. (c) Sketch for
 shoreline regression after autobreak



Figure 3. Model variables, including the enthalpy function *H*, the basement elevation *E*, and the

fluvial surface elevation respect to the current sea level *h*, under (a) sea-level fall and SH

regression, (b) sea-level rise and SH transgression, and (c) SH regression after autobreak.





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Figure 4. Sketch of discrete domain. In general the locations of the SH and the ABT, *s* and *r* respectively, are in between two nodes of our discrete domain.

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Figure 5. Model runs under square root sea-level fall with (a) $R_{ab} = 0.8$, $\lambda_Z = -0.3$, and (b) $R_{ab} = 0.2$, $\lambda_Z = -0.3$. At the bottom, we include a comparison of boundary trajectories of the analytical (solid-lines) and numerical (circles) solutions. At the top, we depict the evolution of the longitudinal profile over time.



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Figure 6. Stratigraphies produced under sea-level cycling for three different values of the dimensionless group $R_{ab} = q_0/(\beta v)$. Videos showing the evolution over time are available in the supplementary material.



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Figure 7. (a) ABT and SH trajectories under sea-level cycles (i.e., Z = sin(t)) and $R_{ab} = 0.5$. Shaded intervals correspond to intervals of river incision during sea-level rise. (b) Plot of ABT residuals, r_{res} , and defining the time lag τ , as a function of the ABT residual. (c) Plot of SH residuals, s_{res} .



Figure 8. (a) Values for the delay in ABT response to sea-level rise as a function of the dimensionless group $R_{ab} = q_0/(\beta v)$, and the amplitude of the sea-level cycles *A*. (b) Sediment

volume eroded during sea-level rise, also as a function of R_{ab} and A.



Figure 9. a) Sea-level curves showing the times for the onset of sea-level rise t_s , and at the 743 conclusion of river incision under sea-level rise for different R_{ab} values (i.e., t_{EI} for $R_{ab} = 0.2$, 744 t_{E2} for $R_{ab} = 0.5$, and t_{E3} for $R_{ab} = 0.8$). Below, longitudinal profiles depicting the sections at 745 the onset of sea-level rise (dashed line), and at the conclusion of river incision under sea-level 746 rise (solid line) under (b) $R_{ab} = 0.2$, (c) $R_{ab} = 0.5$, and (d) $R_{ab} = 0.8$. Note that under $R_{ab} =$ 747 0.8, although the ABT does not migrate seawards, sediment erodes from the mid portion of the 748 fluvial surface during sea-level rise. The stratigraphic profiles for the three model runs are 749 included in Figure 6, and the ABT and SH trajectories for the $R_{ab} = 0.5$ scenario are included in 750 Figure 7a. 751

753 Appendix:



Figure A1. Comparison of analytical (solid lines) and numerical (circles) ABT and SH
 trajectories under square-root sea-level rise.



Figure A2. Comparison of analytical (solid lines) and numerical (circles) ABT and SH
 trajectories under square-root sea-level fall.

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Figure A3. Comparison between analytical and numerical predictions of the moving boundary parameters λ_{sh} and λ_{ab} for the sea-level fall (circles) and sea-level rise (triangles) scenarios. The solid-line is the analytical solution and the symbols represent the enthalpy numerical solution described in section 4. We use $\Delta x = 0.01$ and $\Delta t = 5 \cdot 10^{-5}$.





Figure A4. Comparison of analytical (dashed) and numerical (solid) ABT and SH trajectories under constant sea-level rise with $\Delta x = 0.01$ and $\Delta t = 5 \cdot 10^{-5}$.



- **Figure A5.** Comparison of analytical (solid lines) and numerical (symbols) delta length values
- 775 (i.e., s r) at steady state.

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